Contact problems: roller bearing and impact of a lorry.



Sheet metal forming

Crash of a car against a deformable barrier



Self-contact of a car component Crash of a car against a deformable barrier



Contact of tyres with a road surface,



Contact in a Mass Spring System



Point mass supported by spring Energy of the mass spring system

The Energy of system

$$\Pi(u) = \frac{1}{2} \, k \, u^2 - m \, g \, u$$

The variation of Energy

$$\delta \Pi(u) = k \, u \, \delta u - m \, g \, \delta u = 0$$

The second variation of Π

$$\delta^2 \Pi = k$$

The minimum of u

$$u = \frac{m g}{k}$$

The restriction of the motion of the mass by a rigid support

$$c(u) = h - u \ge 0$$



the point mass contacts the rigid surface, a reaction force R_N appears.

 $R_N \leq 0$

two cases within a contact problem

c(u) > 0 and $R_N = 0$

 $c(u) = 0 \quad \text{and} \ R_N < 0$

Both cases can be combined

 $c(u) \ge 0$, $R_N \le 0$ and $R_N c(u) = 0$

Kuhn-Tucker condition

$$c(u) = h - u \ge 0$$

Lagrange multiplier method

the Lagrange multiplier method adds to the energy o the system a term which contains the constraint

$$\Pi(u,\lambda) = \frac{1}{2} k u^2 - m g u + \lambda c(u)$$

the Lagrange multiplier λ is equivalent to the reaction force R_N .

$$k u \, \delta u - m g \, \delta u - \lambda \, \delta u = 0$$
$$c(u) \, \delta \lambda = 0$$

for contact: u = h

$$\lambda = k h - m g = R_N$$

for does not contact: R_N =0



Penalty method

or an active constraint one adds a penalty term to the energy

$$\Pi(u) = \frac{1}{2} k u^2 - m g u + \frac{1}{2} \epsilon [c(u)]^2 \quad \text{with } \epsilon > 0$$

The variation of the energy

$$k \, u \, \delta u - m \, g \, \delta u - \epsilon \, c(u) \, \delta u = 0$$

the solution

$$u = (m g + \epsilon h) / (k + \epsilon)$$
$$c(u) = h - u = \frac{k h - m g}{k + \epsilon}$$

penalty spring due to the penalty term



Penalty method $c(u) = h - u = \frac{k h - m g}{k + \epsilon}$ in the contact, $mg \ge kh$

Penetration of the point mass into the rigid support occurs.

$$\epsilon \to \infty \implies c(u) \to 0$$

$$\epsilon \rightarrow 0$$
 the unconstrained solution.

The reaction force

$$R_N = \lambda = \epsilon c(u) = \frac{\epsilon}{k + \epsilon} (kh - mg)$$

 $\epsilon \rightarrow \infty$ the correct solution obtained with the Lagrange multiplier method. $\lambda = k h - m g = R_N$



m

Lagrange method



Lagrange method
$$\Pi = \frac{1}{2} \int_{(l)} EA [u'(x)]^2 dx - \sum_i F_i u(x_i)$$
$$\Pi = \frac{1}{2} \frac{EA}{l} \left[u_1^2 + (u_2 - u_1)^2 + u_3^2 \right] - F u_1$$
$$\delta \Pi = \frac{EA}{l} \left[u_1 \, \delta u_1 + (u_2 - u_1) \left(\delta u_2 - \delta u_1 \right) + u_3 \, \delta u_3 \right] - F \, \delta u_1 = 0$$
$$u_2 - u_3 \leq g$$

For
$$u_2 - u_3 < g$$

 $\langle \delta u_1, \delta u_2, \delta u_3 \rangle \begin{cases} \frac{EA}{l} (2u_1 - u_2) - F \\ \frac{EA}{l} (u_2 - u_1) \\ \frac{EA}{l} u_3 \end{cases} \end{cases} = 0$

Lagrange method

$$F > EA \frac{g}{l} \qquad u_2 - u_3 = g$$
$$\Pi_{LM} = \Pi + \lambda g = \Pi + \lambda (g + u_3 - u_2)$$

$$\delta \Pi_{LM} = \delta \Pi + \lambda \left(\delta u_3 - \delta u_2 \right) + \delta \lambda \left(g + u_3 - u_2 \right) = 0$$

$$\left\langle \delta u_1, \delta u_2, \delta u_3, \delta \lambda \right\rangle \left\{ \begin{array}{l} \frac{EA}{l} \left(2u_1 - u_2 \right) - F \\ \frac{EA}{l} \left(u_2 - u_1 \right) - \lambda \\ \frac{EA}{l} u_3 + \lambda \\ g + u_3 - u_2 \end{array} \right\} = 0$$

Lagrange method

$$\begin{bmatrix} 2\frac{EA}{l} & -\frac{EA}{l} & 0 & 0\\ -\frac{EA}{l} & \frac{EA}{l} & 0 & -1\\ 0 & 0 & \frac{EA}{l} & 1\\ 0 & -1 & 1 & 0 \end{bmatrix} \begin{cases} u_1\\ u_2\\ u_3\\ \lambda \end{cases} = \begin{cases} F\\ 0\\ 0\\ -g \end{cases}$$

$$u_{2} = \frac{1}{3} \left(2g + \frac{Fl}{EA} \right) \qquad \lambda = \frac{1}{3} \left(EA \frac{g}{l} - F \right)$$
$$F = EA \left(3\frac{u_{2}}{l} - 2\frac{g}{l} \right)$$

Penalty method







 $\mathcal{E} \to \infty$